



RTA Application Note How to import an LDF file

RTA-CAR



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Contents

1	Introduct	ion	6
	1.1	Scope	6
	1.2	Preconditions	6
	1.3	Import LDF in ISOLAR-AN-000	6
	1.3.1	LDF Importer	6
	1.3.2	Select ECU and Frames	7
	1.3.3	BSW Configuration	9
	1.3.4	BSW Code generation	10
	1.3.5	RTE integration	11
	1.3.6	MCAL Integration	12
	1.3.7	Update build environment	12
2	Contact,	Support and Problem Reporting	13

RTA Application Note How to import an LDF file



List of Tables

RTA Application Note How to import an LDF file



List of Figures

How to import an LDF file



1 Introduction

1.1 Scope

This application note will shows how to create a Lin node importing the relative LDF file. In this example, the Lin node will be imported in an existing ECU with CAN node already configured.

1.2 Preconditions

- ECU name in LDF is matching with the existing ECU in the System
- BSW makes use of the RTA-BSW configurator generator
- RTE, BSW and OS are generating with no issue

1.3 Import LDF in ISOLAR-AN-000

1.3.1 LDF Importer

Select LDF import feature from ISOLAR-A

Project RTE RTA-BSW Run Role Configuration	Window Help
• N F 📀 10 🗮 🛠 🖓 🔍 🔍 🙆 🖸 🕒	Q 💿 🖻 🙀 🏶 🏇 ·
:or 🛛 🙀 Filesystem Navigator 📃 🗖	をDF Importer
□ 🔄 🖾 🗸	
*	

Select the LDF file from your file system. Select the ECU name (even if it's already selected, open the Ecu name menu and select the ECU to activate the merge option):

How to import an LDF file



强 Import LDF													
Select File Package with the Same Name Exists in the File													
LDF File Name Isers	LDF File Name Isers\bal9yok_Project\support\Mahle\3500_LDF_Inport\LIN_Net2_CR_MY18.ldf + Browse												
Network													
Network Type Standard LIN Cluster Name LinCluster_0 Ecu Name BMS													
											ARPackage Nan Please click the	ne Browse button to configure ARPackage and File name.	
											File Name	DBC_SysDesc.arxml	Browse
Package Name	DBC_SysDesc_Can_Network	File Merge Preferences											
?	< Back Next > Finis	h Cancel											

In File Merge Preferences selected the wanted merge option.

1.3.2 Select ECU and Frames

In the next window select the required Master ECU, and then the Lin frames:

How to import an LDF file



ontroller Name	Frame Name	Direction	Type	Protocol	ECU Name
BMS					BMS
	StatusPrVaneL	Receive	COM	LIN	
	StatusPrVaneR	Receive	COM	LIN	
	StatusPar_HGS	Receive	COM	LIN	
	StatusPwSieve	Receive	COM	LIN	
	SlaveResp	Receive	DIAGRonse	LIN	
	StatusPpSieve	Receive	COM	LIN	
	StatusPropAct	Receive	COM	LIN	
	SetMovePar_HGS	Transmit	COM	LIN	
	SetMovewSieve	Transmit	COM	LIN	
	OutSynch	Transmit	COM	LIN	
	✓ MasterReq	Transmit	DIAGRequest	LIN	
	SetMovepSieve	Transmit	COM	LIN	
	SetMoveropAct	Transmit	COM	LIN	
	SetMoverVaneL	Transmit	COM	LIN	
	SetMoverVaneR	Transmit	COM	LIN	

As result of the import, ISOLAR-A will create PDU, Frames and Signals. It will also create a new Lin network:





1.3.3 BSW Configuration

It is now possible to generate the BSW configuration RTA-BSW will create the configuration for the new modules LinIf and LinSM:



The following actions needs to be added to the initialization of the ECU to complete the BSW integration:

- 1. Initialize LinIf
- 2. Initialize LinSM
- 3. ComM allow communication on Lin channel
- 4. ComM set FULL COMM for Lin channel
- 5. Lin Schedule tables shall be activated

All these action can be implemented by BswM adding them in the BswMActions and BswMActionLists.

NB: Point 1 to 4 are same as any ComM channel (e.g. CAN nodes), while point 5 is dedicated for Lin channels.

The following pictures show a sample configuration:

How to import an LDF file





1.3.4 BSW Code generation

It's now possible to generate the BSW code. RTA-BSW will update the COM stack modules with the new configuration and will create the LinIf and LinSM source code:

How to import an LDF file

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🦢 settings	
🗁 src	
a 🗁 BSW	
🔺 🗁 G	en
Þ 💪	∋ Bfx
Þ 💪	∋ BswM
Þ 🖻	∋ CanIf
Þ 🖻	∋ CanNm
Þ 🖻	∋ CanSM
Þ 🖻	∋ CanTp
Þ 🖻	∋ Com
Þ 🖻	∋ ComM
Þ 🖻	ComStack
Þ 🖻	conf_proc_log
Þ 🙆	> Crc
Þ 🙆	🕁 Dcm
Þ 🔎	🕁 Dem
Þ 🖻	∋ Det
Þ 🖻	→ E2E
Þ 🔎	∋ EcuM
Þ 🙆	⇒ Fee
Þ 🔎	FeeFs1
Þ 🔎	∋ Fim
	Integration
Þ 🙆	LinIf
Þ 🙆	LinSM
Þ	Memlf
Þ 🖻	∋ Nm
Þ 🖻	∋ NvM
Þ 🖻	∋ PduR
Þ 🖻	Platform
Þ 🖻	∋ rba_ArxmlGen
Þ	⇒ WdgIf
Þ	∋ WdgM
Þ	→ Xcp
	BCT_generated.txt
	CodeGen_version.h

1.3.5 RTE integration

From ECU Configurator open the Rte modules and add the LinSM and LinIf module instance. This step is BSW module equivalent of adding a SWC to the Composition



Now in the RTE Editor, Entity to Task Mapping window, map the LinIf, LinSM and the new ComM MainFunction to a task

BMS	×																
intity	y to Task N	lapping															
▼ F	Properties and	Filter Section															
Thi	is section displ	ays the properti	ies of E	cucValueCollection and filte	ers for OsAppli	cations and E	EcuPartiti	ion.									
0	IS Conf:	OsCfg			• RTE Conf:	Rte_Cfg			•	ECU C	Conf:		•	ECU Extract: EXTR_	BMS		
0	S Application:				• Partition:					Core:							
Mapp (±	ed Entities	g: 43/43 🖲	Create	Report 📎 Filter :					■ - ⊗ ⇔ 8 ⊟ ;		UnMa	apped Entities					
	Os Task/	s Task/Event Mapping Component Instance Properties					Position Swc Event Properti.				Œ	E Showing: 3/164 Screate Report S Filter :					
	OsTask		Os	Entities	ComponentIr	istance	Pos	Act	Event			Entities Properties	Component Instance Pr ComponentInstance	Event Properties	Component OcTack		
_		Y	Y	Y		. Y		Y				onnapped/enomeous		Event type	Y		
9				KRE_Com_SWC	CPT_Com	SWC	7	0.0	TE_Com_SWC_1		1	BSWSE_MainFuncti	♦ ComM	BswTimingEvent			
10				A RE_Swc_Dem_Periodic	CPT_Qag_	SWC	8	0.0	TE_Swc_Dem_P		2	BSWSE_MainFuncti	♦ LinIf	BswTimingEvent			
11	▲	c_BSW	20								3	BSWSE_MainFuncti	♦ LinSM	BswTimingEvent			
12				MainFunction	♦ BSWIMPL_	BswM	11	0.0	TE_BswM_Main								
13				BSWSE_MainFunctio	BSWIMPL_	Can	12	0.0	BSWTE_MainFu		-						
14				BSWSE_MainFunctio	BSWIMPL_	Can	13	0.0	BSWTE_MainFu		-						
15				BSWSE_MainFunctio	BSWIMPL_	Can	14	0.0	BSWTE_MainFu		-						
16				 BSWSE_MainFunctio 	BSWIMPL_	Can	15	0.0	BSWTE_MainFu								

Then generate the RTE.

1.3.6 MCAL Integration

Lin driver shall be configured in the MCAL generation tool. The driver configuration does not contains information about frames (which means that frames does not have to be aligned) but it contains Channel configuration that shall be aligned to the BSW configuration. RTA-BSW generates a Lin configuration, but is limited to the LinChannels, this configuration can be imported into MCAL, but the driver will require additional configuration which are not dependent by the BSW. After the Lin has been configured and generated, it may requires to be integrated in the system for: - MainFunciton: scheduled by task - Init: invoked by EcuM in the InitList

1.3.7 Update build environment

When all the new module have been generated, is time to update the build environment to add this module to the building list. During the phase some integration files may required adaption to integrate the BSW with the MCAL.



2 Contact, Support and Problem Reporting

For details of your local sales office as well as your local technical support team and product hotlines, take a look at the ETAS website:

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